



6

Scheduling

Uwe R. Zimmer - The Australian National University



Scheduling

Motivation and definition of terms

Purpose of scheduling



Scheduling

References for this chapter

[Ben2006]
Ben-Ari, M
Principles of Concurrent and Distributed Programming
second edition, Prentice-Hall 2006

[AdaRM2012]
Ada Reference Manual - Language and Standard Libraries,
ISO/IEC 8652:201x (E)

[Stallings2001]
Stallings, William
Operating Systems
Prentice Hall, 2001



Scheduling

Motivation and definition of terms

Purpose of scheduling

Two scenarios for scheduling algorithms:

1. Ordering resource assignments (CPU time, network access, ...).
IEEE live, on-line application of scheduling algorithms.
2. Predicting system behaviours under anticipated loads.
IEEE simulated, off-line application of scheduling algorithms.

Predictions are used:

- *at compile time*: to confirm the feasibility of the system, or to predict resource needs, ...
- *at run time*: to permit admittance of new requests or for load-balancing, ...



Scheduling

Motivation and definition of terms

Criteria

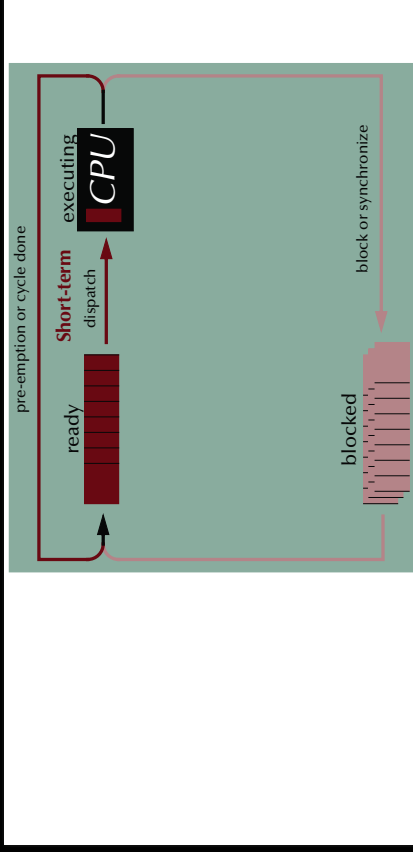
Process / user perspective:	minimize the ...	Predictability criteria:	minimize deviation from given ...
Waiting time	minima / maxima / average / variance		value / minima / maxima
Response time	minima / maxima / average / variance		value / minima / maxima / deadlines
Turnaround time	minima / maxima / average / variance		value / minima / maxima / deadlines
System perspective:	maximize the ...		
Throughput	minima / maxima / average		
Utilization	CPU busy time		



Scheduling

Definition of terms

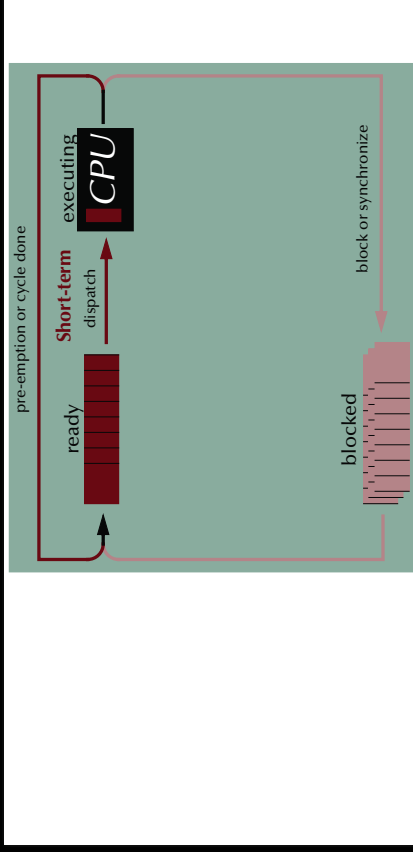
Time scales of scheduling



Scheduling

Definition of terms

Time scales of scheduling



Scheduling

Motivation and definition of terms

Criteria

Process / user perspective:	minimize the ...	Predictability criteria:	minimize deviation from given ...
Waiting time	minima / maxima / average / variance		value / minima / maxima
Response time	minima / maxima / average / variance		value / minima / maxima / deadlines
Turnaround time	minima / maxima / average / variance		value / minima / maxima / deadlines
System perspective:	maximize the ...		
Throughput	minima / maxima / average		
Utilization	CPU busy time		



Scheduling

Definition of terms

Time scales of scheduling

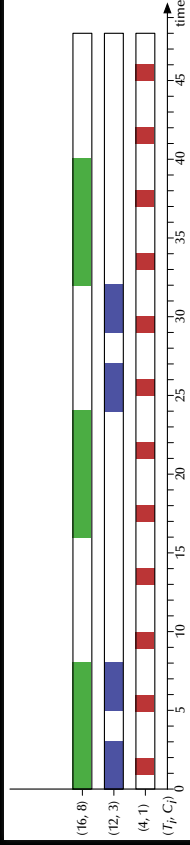




Scheduling

Performance scheduling

Requested resource times



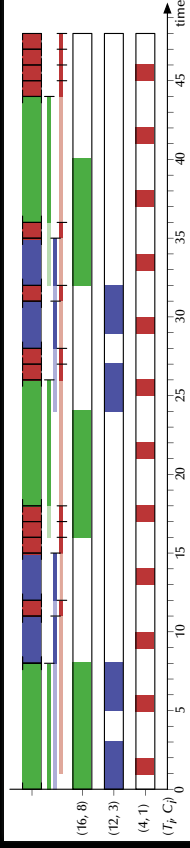
Tasks have an average time between instantiations of
and a constant computation time of



Scheduling

Performance scheduling

First come, first served (FCFS)



Waiting time: 0..11, average: 5.9 – Turnaround time: 3..12, average: 8.4

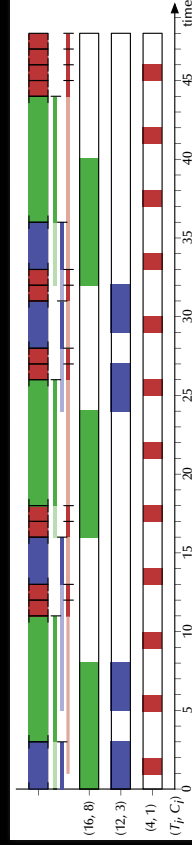
As tasks apply *concurrently* for resources, the actual sequence of arrival is non-deterministic.
 ↳ hence even a deterministic scheduling schema like FCFS can lead to different outcomes.



Scheduling

Performance scheduling

First come, first served (FCFS)



Waiting time: 0..11, average: 5.4 – Turnaround time: 3..12, average: 8.0

↳ In this example:
 the average waiting times vary between 5.4 and 5.9
 the average turnaround times vary between 8.0 and 8.4

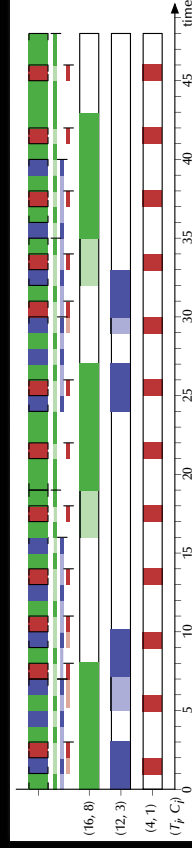
↳ **Shortest possible maximal turnaround time!**



Scheduling

Performance scheduling

Round Robin (RR)



Waiting time: 0..5, average: 1.2 – Turnaround time: 1..20, average: 5.8

↳ Optimized for swift initial responses.

↳ "Stretches out" long tasks.

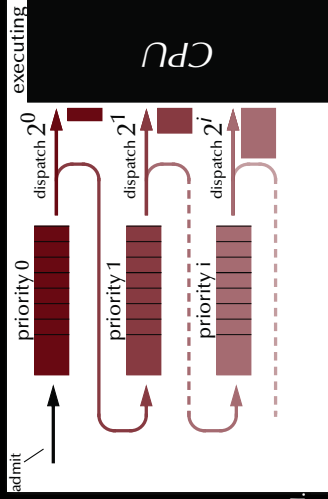
↳ **Bound maximal waiting time!** (depended only on the number of tasks)



Scheduling

Performance scheduling

Feedback with 2^i pre-emption intervals



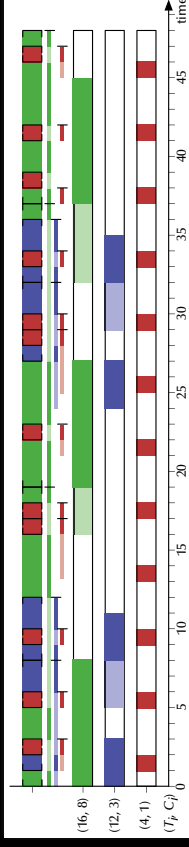
- Implement multiple hierarchical ready-queues.
 - Fetch processes from the highest filled ready queue.
 - Dispatch more CPU time for lower priorities (2^i units).
- ☞ Processes on lower ranks may suffer **starvation**.
- ☞ New and short tasks will be preferred.



Scheduling

Performance scheduling

Feedback with 2^i pre-emption intervals - sequential



Waiting time: 0.5, average: 1.5 – Turnaround time: 1.21, average: 5.7

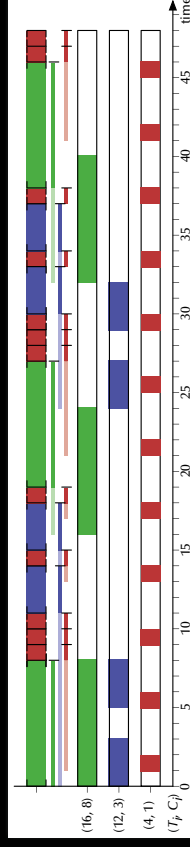
- ☞ Optimized for swift initial responses.
- ☞ Prefers short tasks and long tasks can suffer starvation.
- ☞ **Very short initial response times!** and good average turnaround times.



Scheduling

Performance scheduling

Shortest job first



Waiting time: 0.11, average: 3.7 – Turnaround time: 1.14, average: 6.3

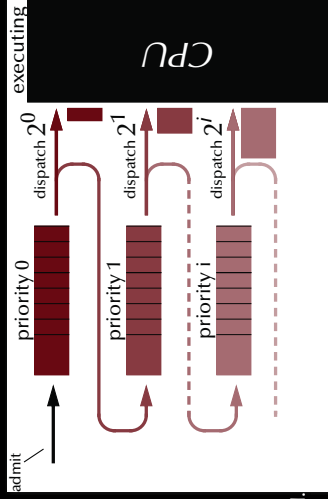
- ☞ Optimized for good average performance with minimal task-switches.
- ☞ Prefers short tasks but all tasks will be handled.
- ☞ **Good choice if computation times are known and task switches are expensive!**



Scheduling

Performance scheduling

Feedback with 2^i pre-emption intervals - overlapping



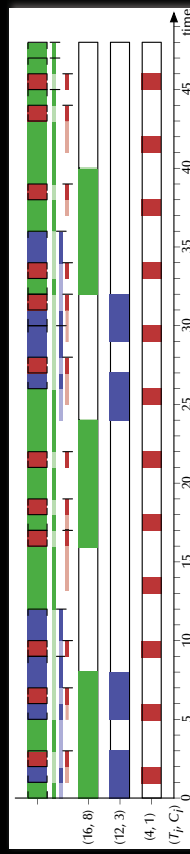
- Implement multiple hierarchical ready-queues.
 - Fetch processes from the highest filled ready queue.
 - Dispatch more CPU time for lower priorities (2^i units).
- ☞ Processes on lower ranks may suffer **starvation**.
- ☞ New and short tasks will be preferred.



Scheduling

Performance scheduling

Feedback with 2^i pre-emption intervals - overlapping



Waiting time: 0.3, average: 0.9 – Turnaround time: 1.45, average: 7.7

- ☞ Optimized for swift initial responses.
- ☞ Prefers short tasks and long tasks can suffer **starvation**.
- ☞ **Long tasks are delayed until all queues run empty!**

Scheduling

Performance scheduling

Shortest job first

Waiting time: 0..10, average: 3.4 – Turnaround time: 1..14, average: 6.0

- ☞ Can be sensitive to non-deterministic arrival sequences.

© 2020 Uwe R. Zimmer, The Australian National University page 444 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Performance scheduling

Highest Response Ratio $\frac{W_i + C_i}{C_i}$ First (HRRF)

Waiting time: 0..9, average: 4.1 – Turnaround time: 2..13, average: 6.6

- ☞ Blend between Shortest-Job-First and First-Come-First-Served.
- ☞ Prefers short tasks but long tasks gain preference over time.
- ☞ More task switches and worse averages than SJF but better upper bounds!

© 2020 Uwe R. Zimmer, The Australian National University page 445 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Performance scheduling

Shortest Remaining Time First (SRTF)

Waiting time: 0..6, average: 0.7 – Turnaround time: 1..21, average: 4.4

- ☞ Optimized for good averages.
- ☞ Prefers short tasks and long tasks can suffer starvation..
- ☞ Better averages than Feedback scheduling but with longer absolute waiting times!

© 2020 Uwe R. Zimmer, The Australian National University page 446 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Performance scheduling

Comparison (in order of appearance)

© 2020 Uwe R. Zimmer, The Australian National University page 447 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Performance scheduling

Comparison by shortest maximal waiting

☞ Providing upper bounds to waiting times ☞ Swift response systems

© 2020 Uwe R. Zimmer, The Australian National University page 448 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Performance scheduling

Comparison by shortest average waiting

☞ Providing short average waiting times ☞ Very swift response in most cases

© 2020 Uwe R. Zimmer, The Australian National University page 449 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Performance scheduling

Comparison by shortest maximal turnaround

☞ Providing upper bounds to turnaround times ☞ No tasks are left behind

© 2020 Uwe R. Zimmer, The Australian National University page 450 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Performance scheduling

Comparison by shortest average turnaround

☞ Providing good average performance ☞ High throughput systems

© 2020 Uwe R. Zimmer, The Australian National University page 451 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Performance scheduling

Comparison overview

	Selection	Pre-emption	Waiting	Turnaround	Preferred jobs	Starvation possible?
Methods without any knowledge about the processes						
FCFS	$\max(W_i)$	no	long	long average & short maximum	equal	no
RR	equal share	yes	bound	good average & large maximum	short	no
FB	priority queues	yes	very short	short average & long maximum	short	no
Methods employing computation time C_i and elapsed time E_i						
SJF	$\min(C_i)$	no	medium	medium	short	yes
HRRF	$\max(\frac{W_i + C_i}{C_i})$	no	controllable compromise	controllable compromise	controllable	no
SRTF	$\min(C_i - E_i)$	yes	very short	wide variance	short	yes

© 2020 Uwe R. Zimmer, The Australian National University page 452 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Predictable scheduling

Towards predictable scheduling ...

Task requirements (Quality of service):

- ☞ Guarantee **data flow** levels
- ☞ Guarantee **reaction** times
- ☞ Guarantee **deadlines**
- ☞ Guarantee **delivery** times
- ☞ Provide **bounds** for the **variations** in results

Examples:

- Streaming media broadcasts, playing HD videos, live mixing audio/video, ...
- Reacting to users, Reacting to alarm situations, ...
- Delivering a signal to the physical world at the required time, ...

© 2020 Uwe R. Zimmer, The Australian National University page 453 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Predictable scheduling

Temporal scopes

Common attributes:

- Minimal & maximal delay after creation
- Maximal elapsed time
- Maximal execution time
- Absolute deadline

© 2020 Uwe R. Zimmer, The Australian National University page 454 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Predictable scheduling

Temporal scopes

Common attributes:

- Minimal & maximal delay after creation
- Maximal elapsed time
- Maximal execution time
- Absolute deadline

© 2020 Uwe R. Zimmer, The Australian National University page 455 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Predictable scheduling

Temporal scopes

Common attributes:

- Minimal & maximal delay after creation
- Maximal elapsed time
- Maximal execution time
- Absolute deadline

© 2020 Uwe R. Zimmer, The Australian National University page 456 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Predictable scheduling

Temporal scopes

Common attributes:

- Minimal & maximal delay after creation
- Maximal elapsed time
- Maximal execution time
- Absolute deadline

© 2020 Uwe R. Zimmer, The Australian National University page 457 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Predictable scheduling

Common temporal scope attributes

Temporal scopes can be:

Periodic	☞ controllers, routers, schedulers, streaming processes, ...
Aperiodic	☞ periodic 'on average' tasks, i.e. regular but not rigidly timed, ...
Sporadic / Transient	☞ user requests, alarms, I/O interaction, ...

Deadlines can be:

Semantics defined by application	"Hard"	☞ single failure leads to severe malfunction and/or disaster
	"Firm"	☞ results are meaningless after the deadline
	"Soft"	☞ only multiple or permanent failures lead to malfunction

© 2020 Uwe R. Zimmer, The Australian National University page 458 of 758 (chapter 6: "Scheduling" up to page 459)

Scheduling

Summary

Scheduling

- **Basic performance scheduling**
 - Motivation & Terms
 - Levels of knowledge / assumptions about the task set
 - Evaluation of performance and selection of appropriate methods
- **Towards predictable scheduling**
 - Motivation & Terms
 - Categories & Examples

© 2020 Uwe R. Zimmer, The Australian National University page 459 of 758 (chapter 6: "Scheduling" up to page 459)

